# Operating Instructions

## DAL-311x7x0S
*Resistance values: 1 kΩ, 10 kΩ, 100 kΩ*

## Technical features:

- red display of -19999…99999 digits (optional: green, orange, blue)
- installation: 120 mm without plug-in terminal
- min/max-memory
- 30 adjustable setpoints
- display flashing at threshold value exceedance / threshold value undercut
- zero-key for triggering of Hold, Tara
- permanent min/max-value recording
- volume metering (totaliser)
- mathematic functions like reciprocal value, square root, squaring or rounding
- setpoint generator
- sliding average determination
- brightness control
- programming interlock via access code
- protection class IP65 at the front side
- plug-in screw terminal
- optional: galvanic isolated digital input
- optional: 1 or 2 analog outputs
- optional: 2 or 4 relay outputs or 8 PhotoMos outputs
- optional: RS232 or RS485 interface
- accessories:     PC-based configuration-kit PM-TOOL with CD & USB-adapter for devices without keypad and for a simple adjustment of standard devices

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## Note

[1] sensor supply
only at 0/4...20 mA,
0...10V DC input

**power supply**
0 100-240V AC
2 10...40V DC galvanic seperated
3 100-240V AC with sensor supply 24V DC/50mA and digital input [1]
4 10...40V DC galvanic seperated with sensor supply 24V DC/50mA and digital input [1]
Y other voltages

**function input**
7 resistance measurement 1k, 10k, 100 kOhm

**function output**
A display + 2 relay outputs (changeover)
B display + 4 relay outputs
C display with analog output 0-10V/4-20mA, switchable
D display + 2 relay with analog output 0-10V/4-20mA, switchable
E display + 4 relay with analog output 0-10V/4-20mA, switchable
Y others outputs

0 standard configuration

S standard, protection IP65

**DAL-311** 7 0 S

# Contents

# 1. Brief description

The panel meter instrument DAL-311 is a 5-digit device for resistance values up to 100 kΩ and a visual threshold value monitoring via the display. The configuration happens via 4 keys at the front or via the optional PC software PM-TOOL. The integrated programming interlock prevents unrequested changes of parameters and can be unlocked again with an individual code. Optional the following functions are available: a supply for the sensor, a digital input for triggering of Hold (Tara), two analog outputs and interfaces for further evaluating in the unit.

With help of the galvanic isolated setpoints (optional), free adjustable limit values can be controlled and reported to a superior master display.

The electrical connection is done via plug-in terminals on the back side.

Selectable functions like e.g. the recall of the min/max-value, an averaging of the measuring signals, a nominal presetting or setpoint presetting, a direct threshold value regulation during operation mode and further measuring setpoints for linearisation, complete the modern device concept.

## 2. Assembly

Please read the *Safety advices* on *page 33* before installation and keep this user manual for future reference.
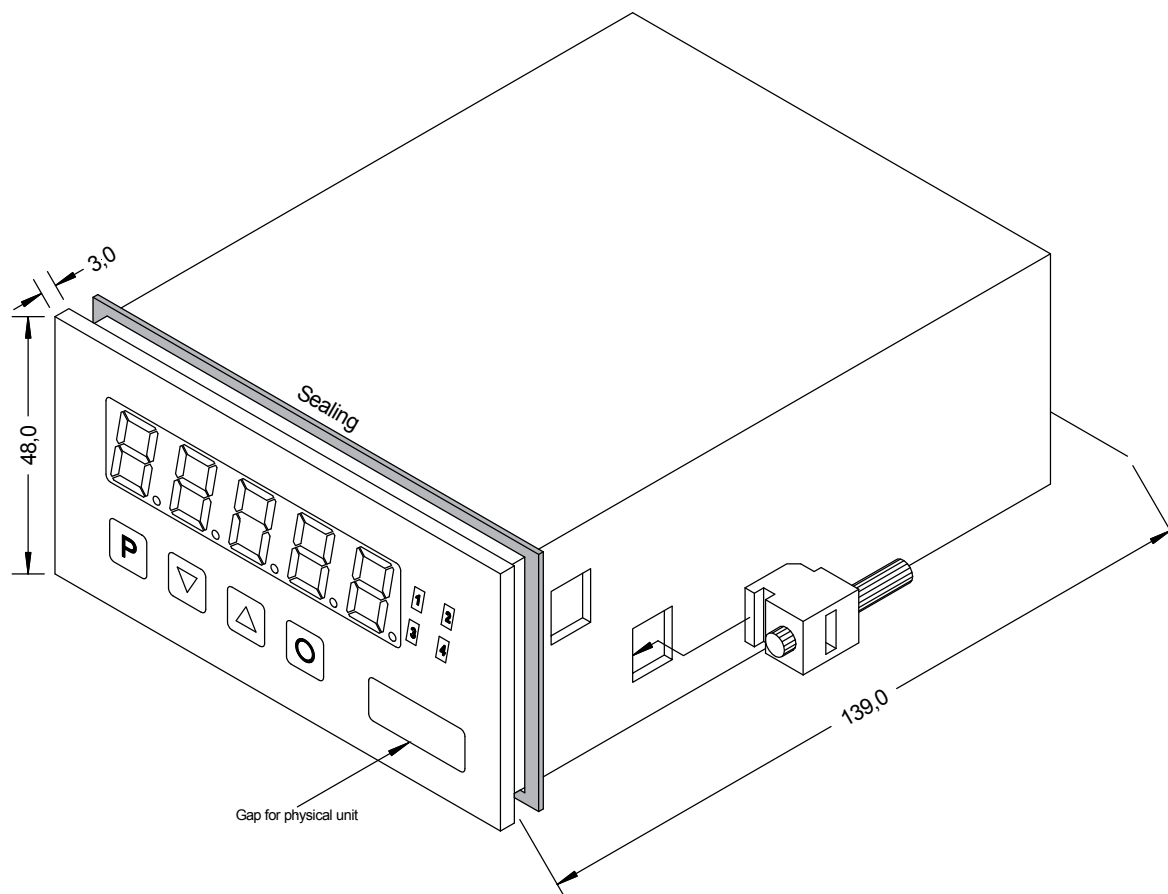


1. After removing the fixing elements, insert the device.
2. Check the seal to make sure it fits securely.
3. Click the fixing elements back into place and tighten the clamping screws by hand. Then use a screwdriver to tighten them another half a turn.
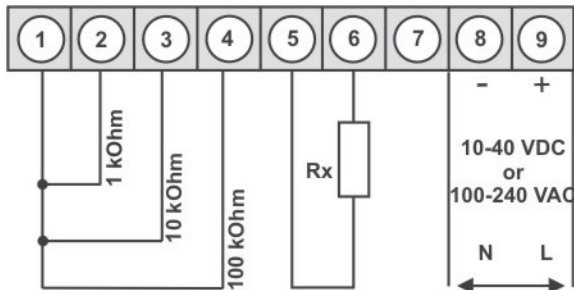
   **CAUTION!   The torque should not exceed 0.1 Nm!**

   **The dimension symbols can be exchanged before installation via a channel on the side!**

# 3. Electrical connection

**Type DAL-311x7x0S**    with a supply of 10-40 VDC galv. isolated, 18-30 VAC
**Type DAL-311x7x0S**    with a supply of 100-240 VAC, DC ±10%



**DAL-311x7x0S with digital input and external voltage source**

Digital input 10-30 VDC

Options:



Analog output 1 | Analog output 2 | Digital input



Relay 1 and 2          Relay 3 and 4
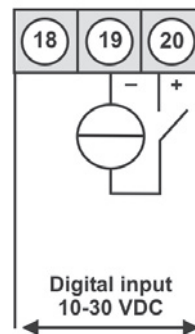


8 PhotoMos-outputs
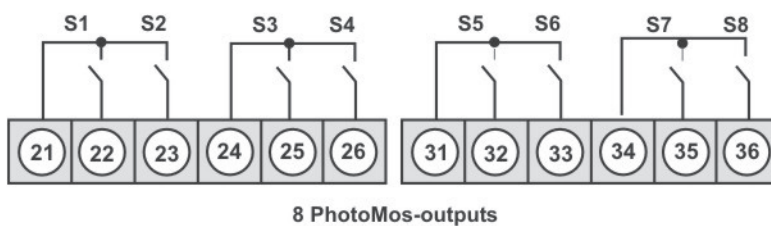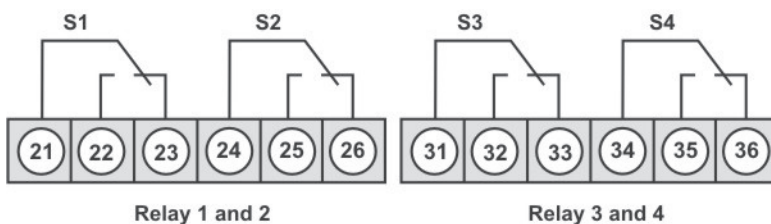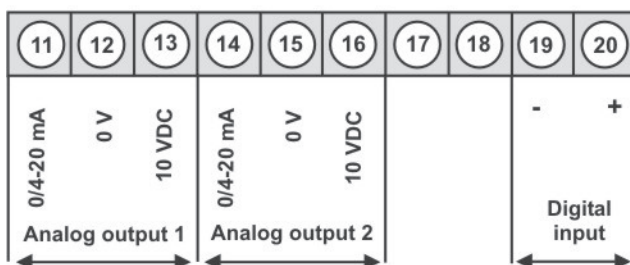
**alternative to analog output 2**



Interface RS232 (Modbus-protocol)          Interface RS485 (Modbus-protocol)

Digital input 10-30 VDC
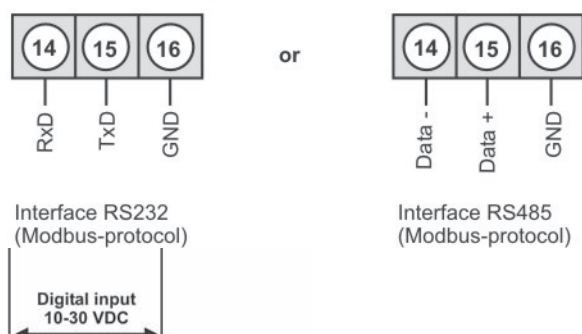
# 4. Description of function and operation

**Operation**
The operation is divided into three different levels.

**Menu level** (delivery status)
This level was designed for the standard settings of the device. Only menu items which are sufficent to set the device into operation are displayed. To get into the professional level, run through the menu level and parameterise *PROF* under menu item *RUN*.

**Menu group level** (complete function volume)
Suited for complex applications as e.g. linkage of alarms, setpoint treatment, totaliser function etc. In this level function groups which allow an extended parameterisation of the standard settings are availabe. To leave the menu group level, run through this level and parameterise *ULOC* under menu item *RUN*.

**Parameterisation level**:
Parameters deposited in the menu item can here be parameterised. Functions, that can be changed or adjusted, are always signalised by a flashing of the display. Settings that are made in the parameterisation level are confirmed with **[P]** and thus saved. Pressing the **[O]-key** („zero-key") leads to a break-off of the value input and to a change into the menu level. All adjustments are saved automatically by the device and changes into operating mode, if no further key operation is done within the next 10 seconds.

| Level | Key | Description |
|---|---|---|
| Menu level | P | Change to parameterisation level and deposited values. |
| | ▲ ▼ | Keys for up and down navigation in the menu level. |
| | O | Change into operation mode. |
| Parameterisation level | P | To confirm the changes made at the parameterisation level. |
| | ▲ ▼ | Adjustment of the value / the setting. |
| | O | Change into menu level or break-off in value input. |
| Menu group level | P | Change to menu level. |
| | ▲ ▼ | Keys for up and down navigation in the menu group level. |
| | O | Change into operation mode or back into menu level. |

## Function chart:
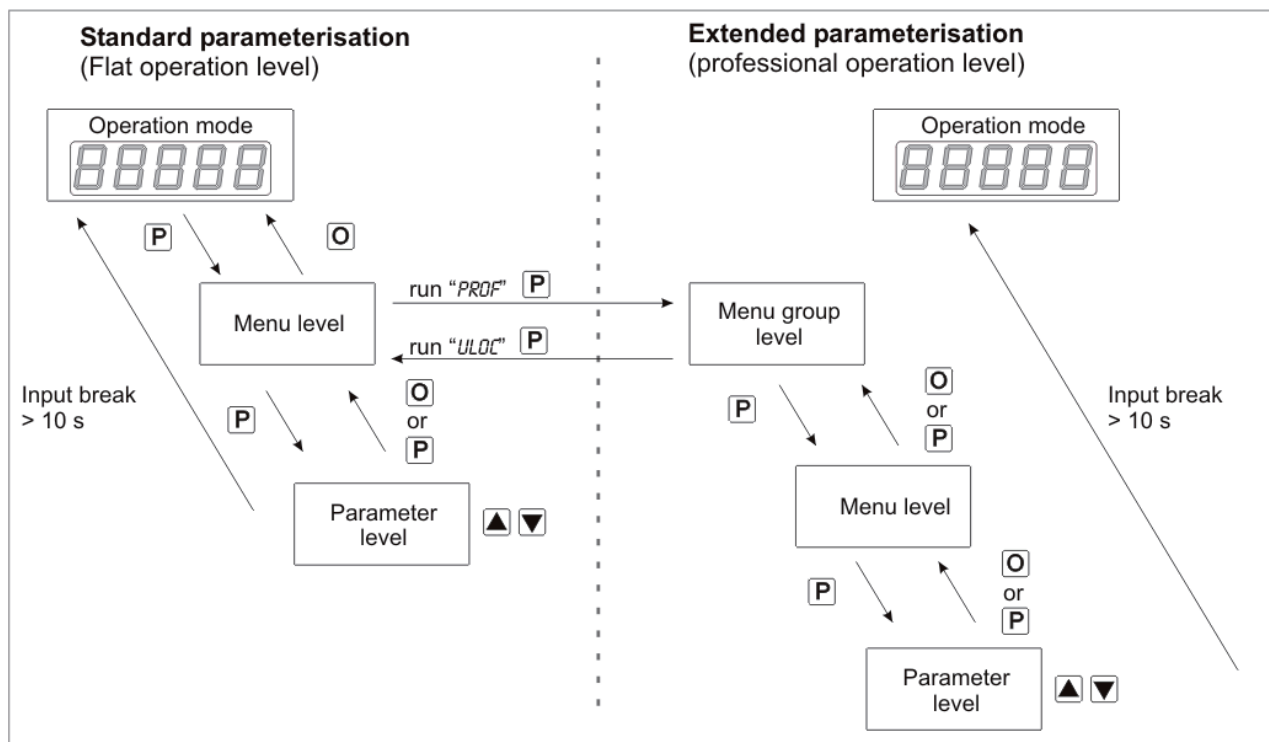


**Underline:**

P  Takeover

O  Stop

▲  Value selection (+)

▼  Value selection (-)

## 4.1 Parameterisation software PM-TOOL:

Part of the PM-TOOL are the software on CD and an USB-cable with device adapter. The connection happens via a 4-pole micromatch-plug on the back side of the device, to the PC-side the connection happens via an USB plug.

System requirements: PC incl. USB interface
Software: Windows XP, Windows VISTA

With this tool the device configuration can be generated, omitted and saved on the PC. The parameters can be changed via the easy to handle program surface, whereat the operating mode and the possible selection options can be preset by the program.

# 5. Setting up the device

## 5.1. Switching on
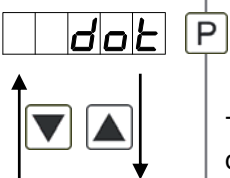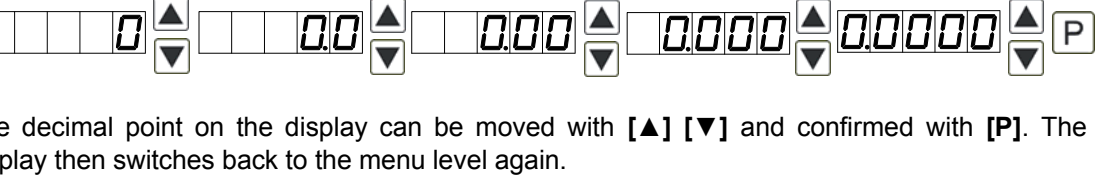
Once the installation is complete, start the device by applying the voltage supply. Before, check once again that all electrical connections are correct.
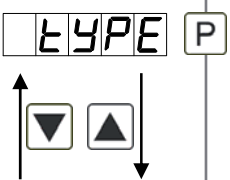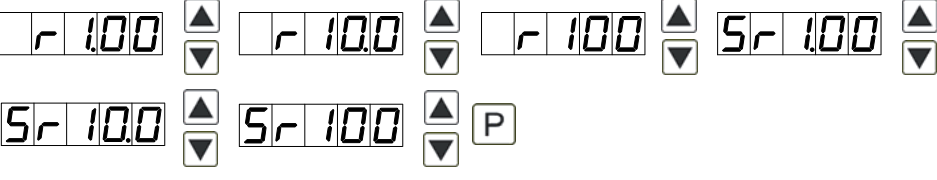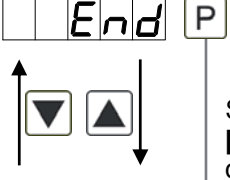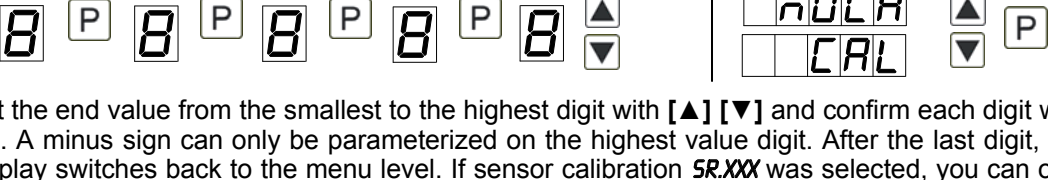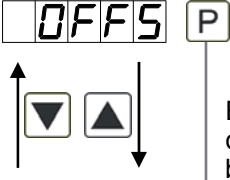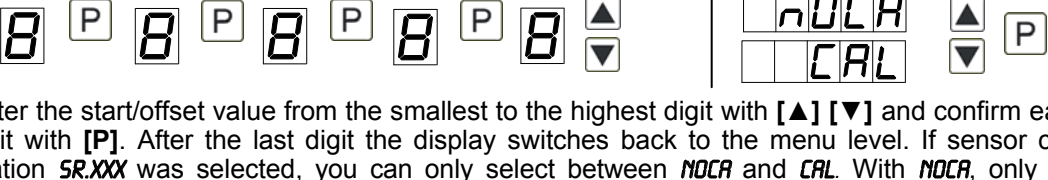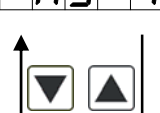
**Starting sequence**
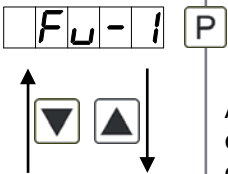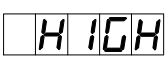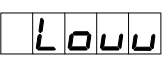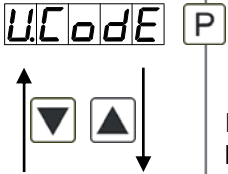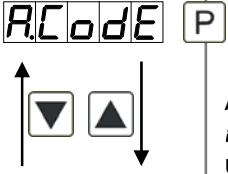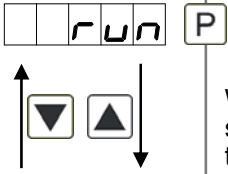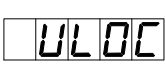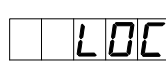
For 1 second during the switching-on process, the segment test (*8 8 8 8 8*) is displayed followed by an indication of the software type and, after that, also for 1 second the software version. After the starting sequence, the device switches to operation/display mode.

## 5.2. Standard parameterisation (Flat operation level)

To parameterise the display, press the **[P]**-key in operating mode for 1 second. The display then changes to the menu level with the first menu item *TYPE*.

| Menu level | Parameterisation level |
|---|---|
|  | **Selection of the input signal, *TYPE*:** <br> **Default:** *SR1.00* (1 kΩ) <br>  <br> As input versions, resistance values of 1, 10 or 100 kΩ signals as factory calibration (without connected sensor signal) and as sensor calibration *SR.XXX* (with connected measuring signal) are available. Confirm your selection with **[P]**. The display then switches back to the menu level again. |
|  | **Setting the end value of the measuring range, *END*:** <br> Default: *10000* <br>  <br> Set the end value from the smallest to the highest digit with **[▲] [▼]** and confirm each digit with **[P]**. A minus sign can only be parameterized on the highest value digit. After the last digit, the display switches back to the menu level. If sensor calibration *SR.XXX* was selected, you can only select between *NOCA* and *CAL*. With *NOCA*, only the previously set display value is taken over, and with *CAL*, the device takes over both the display value and the analogue input value |
|  | **Setting the start/offset value of the measuring range, *OFFS*:** <br> Default: *0* <br>  <br> Enter the start/offset value from the smallest to the highest digit with **[▲] [▼]** and confirm each digit with **[P]**. After the last digit the display switches back to the menu level. If sensor calibration *SR.XXX* was selected, you can only select between *NOCA* and *CAL*. With *NOCA*, only the previously set display value is taken over, and with *CAL*, the device takes over both the display value and the analogue input value. |
|  | **Setting the decimal point, *DOT*:** <br> Default: *0* <br>  <br> The decimal point on the display can be moved with **[▲] [▼]** and confirmed with **[P]**. The display then switches back to the menu level again. |

| Menu level | Parameterisation level |
|---|---|
| **SEC** [P] ▼▲ | **Setting up the display time, SEC:**<br>Default: 1.0<br><br>`00.1` ▲▼ ... `00.9` then `01.0` ▲▼ ... `10.0` ▲▼ [P]<br><br>The display time is set with **[▲] [▼]**. The display moves up in increments of 0.1 up to 1 second and in increments of 1.0 up to 10.0 seconds. Confirm the selection by pressing the **[P]** button. The display then switches back to the menu level again. |
| **Out.rA** [P] ▼▲ | **Selection of analog output, OUT.RA:**<br>Default: 4-20<br><br>`0-10` ▲▼ `0-20` ▲▼ `4-20` ▲▼ [P]<br><br>Three output signals are available: 0-10 VDC, 0-20 mA and 4-20 mA, with this function, the demanded signal is selected. |
| **Out.En** [P] ▼▲ | **Setting up the final value of the analog output, OUT.EN:**<br>Default: 10000<br><br>`8` [P] `8` [P] `8` [P] `8` [P] `8` ▲▼ [P]<br><br>The final value is adjusted from the smallest digit to the highest digit with **[▲] [▼]** and digit by digit confirmed with **[P]**. A minus sign can only be parameterised on the highest digit. After the last digit, the device changes back into menu level. |
| **Out.OF** [P] ▼▲ | **Setting up the initial value of the analog output, OUT.OF:**<br>Default: 00000<br><br>`8` [P] `8` [P] `8` [P] `8` [P] `8` ▲▼ [P]<br><br>The final value is adjusted from the smallest digit to the highest digit with **[▲] [▼]** and digit by digit confirmed with **[P]**. A minus sign can only be parameterised on the highest digit. After the last digit, the device changes back into menu level. |
| **L1-1** [P] ▼▲ | **Threshold values / limits, LI-1:**<br>Default: 2000<br><br>`0` [P] `0` [P] `0` [P] `0` [P] `0` ▲▼ [P]<br><br>This value defines the threshold, that activates/deactivates an alarm. |
| **HY-1** [P] ▼▲ | **Hysteresis for limit values, HY-1:**<br>Default: 00000<br><br>`0` [P] `0` [P] `0` [P] `0` [P] `0` ▲▼ [P]<br><br>The delayed reaction of the alarm is the difference to the threshold value, which is defined by the hysteresis. |

| Menu level | Parameterisation level |
|---|---|
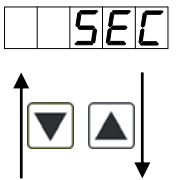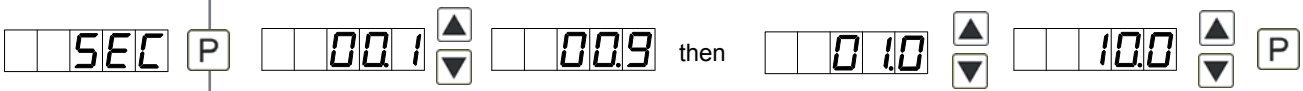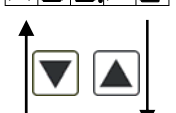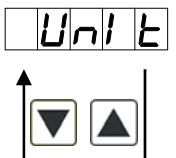
**Function for threshold value undercut / exceedance, _FU-1_:**
Default: _HIGH_

| `Fu-1` [P] | `HIGH` ▲▼ `Louu` ▲▼ [P] |

A limit value undercut is selected with _LOUU_ (for LOW = lower limit value), a limit value exceedance with _HIGH_ (for HIGH = higher limit value). If e.g. limit value 1 is on a threshold level of 100 and allocated with function _HIGH_, an alarm is activated by reaching of the threshold level. If the threshold value was allocated to _LOW_, an alarm will be activated by undercutting the threshold value, as long as the hysteresis is zero.

**The same applies to _LI-1_ to _LI-2_ !**

**User code (4-digit number-combination, free available), _U.CODE_:**
Default: _0000_

| `U.CodE` [P] | `8` [P] `8` [P] `8` [P] `8` ▲▼ [P] |

If this code was set (>0000), all parameters are locked for the user, if _LOC_ has been selected before under menu item _RUN_. By pressing **[P]** for 3 seconds in operation mode, the display shows _CODE_. The _U.CODE_ needs to be entered to get to the reduced number of parameter sets. The code has to be entered befor each parameterisation, until the _A.CODE_ (Master code) unlocks all parameters again.

**Master code (4-digit number-combination, free available), _A.CODE_:**
Default: _1234_

| `A.CodE` [P] | `8` [P] `8` [P] `8` [P] `8` ▲▼ [P] |

All parameters can be unlocked with this code, after _LOC_ has been activated under menu item _RUN_. By pressing **[P]** for 3 seconds in operation mode, the display shows _CODE_ and enables the user to reach all parameters by entering the _A.CODE_. Under _RUN_ the parameterisation can be activated permanently by selecting _ULOC_ or _PROF_, thus at an anew pushing of **[P]** in operation mode, the code needs not to be entered again.

## 5.3. Programming interlock „_RUN_"

**Activation / deactivation of the programming lock or completion of the standard parameterisation with change into menu group level (complete function range), _RUN_:**
Default: _ULOC_

| `run` [P] | `ULOC` ▲▼ `LOC` ▲▼ `ProF` ▲▼ [P] |

With the navigation keys **[▲] [▼]**, choose between the deactivated key lock _ULOC_ (works setting) and the activated key lock _LOC_, or the change into the menu group level _PROF_. Confirm the selection with **[P]**. After this, the display confirms the settings with **"- - - - -"** and switches automatically to operating mode. If _LOC_ was selected, the keyboard is locked. To get back into the menu level, press **[P]** for 3 seconds in operating mode. Now enter the _CODE_ (works setting _1 2 3 4_) that appears using **[▲] [▼]** plus **[P]** to unlock the keyboard. _FAIL_ appears if the input is wrong. To parameterise further functions _PROF_ needs to be set. The device confirms this setting with „- - - - -„ and changes automatically in operation mode. By pressing **[P]** for approx. 3 seconds in operation mode, the first menu group _INP_ is shown in the display and thus confirms the change into the extended parameterisation. It stays activated as long as _ULOC_ or _LOC_ is entered in menu group _RUN_.
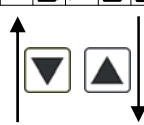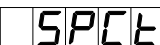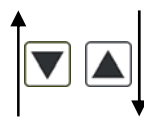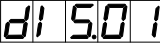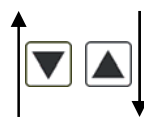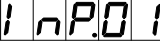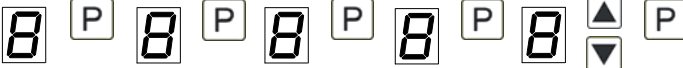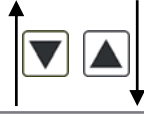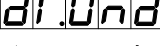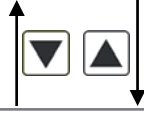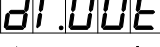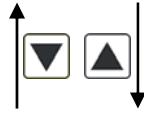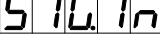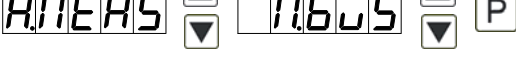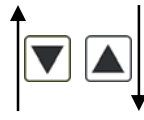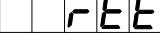
## 5.4. Extended parameterisation (Professional operation level)

### 5.4.1. Signal input parameters

| Menu group level |
|---|



- *InP* - [▲][▼] [P] → Menu level

| Menu level | Parameterisation level |
|---|---|
|  | **Selection of the input signal, *TYPE*:** <br> **Default: *SR1.00* (1 kΩ)** <br>  <br> As input versions, resistance values of 1,10 or 100 kΩ signals as factory calibration (without connected sensor signal) and as sensor calibration *SR.XXX* (with connected measuring signal) are available. Confirm your selection with **[P]**. The display then switches back to the menu level again. |
|  | **Setting the end value of the measuring range, *END*:** <br> Default: *10000* <br>  <br> Set the end value from the smallest to the highest digit with **[▲] [▼]** and confirm each digit with **[P]**. A minus sign can only be parameterized on the highest value digit. After the last digit, the display switches back to the menu level. If sensor calibration *SR.XXX* was selected, you can only select between *NOCA* and *CAL*. With *NOCA*, only the previously set display value is taken over, and with *CAL*, the device takes over both the display value and the analogue input value |
|  | **Setting the start/offset value of the measuring range, *OFFS*:** <br> Default: *0* <br>  <br> Enter the start/offset value from the smallest to the highest digit with **[▲] [▼]** and confirm each digit with **[P]**. After the last digit the display switches back to the menu level. If sensor calibration *SR.XXX* was selected, you can only select between *NOCA* and *CAL*. With *NOCA*, only the previously set display value is taken over, and with *CAL*, the device takes over both the display value and the analogue input value. |
|  | **Setting the comma, decimal point, *DOT*:** <br> Default: *0* <br>  <br> The decimal point on the display can be moved with **[▲] [▼]** and confirmed with **[P]**. The display then switches back to the menu level again. |

| Menu level | Parameterisation level |
|---|---|
| **SEC** ▲▼ | **Setting up the display time, SEC:**<br>Default: 1.0<br><br>SEC [P]   00.1 ▲▼   00.9  then   0 1.0 ▲▼   10.0 ▲▼ [P]<br><br>The display time is set with **[▲] [▼]**. The display moves up in increments of 0.1 up to 1 second and in increments of 1.0 up to 10.0 seconds. Confirm the selection by pressing the **[P]** button. The display then switches back to the menu level again. |
| **EndA** ▲▼ | **Rescaling the measuring input values, ENDA:**<br>Default: 10000<br><br>EndA [P]  8 [P] 8 [P] 8 [P] 8 [P] 8 ▲▼ [P]<br><br>With this function, you can rescale the input value of **e.g**. **9.5 kΩ** (works setting) without applying a measuring signal. |
| **OFFSA** ▲▼ | **Rescaling the measuring input values, OFFA:**<br>Default: 0<br><br>OFFSA [P]  8 [P] 8 [P] 8 [P] 8 [P] 8 ▲▼ [P]<br><br>With this function, you can rescale the input value of **e.g. 1.5 kΩ** (works setting) without applying a measuring signal. |
| **tArA** ▲▼ | **Setting up the tare/offset value, TARA:**<br>**Default: 0**<br><br>tArA [P]  0 [P] 0 [P] 0 [P] 0 [P] 0 ▲▼ [P]<br><br>The given value is added to the linearized value. In this way, the characteristic line can be shifted by the selected amount. |
| **AdJ.Pt** ▲▼ | **Setting up the balance point, ADJ.PT:**<br>**Default: 08000**<br><br>AdJ.Pt [P]  0 [P] 0 [P] 0 [P] 0 [P] 0 ▲▼ [P]<br><br>The balance point for the final value can be chosen (in %) from the measuring range by SRXXX The preset 80.000% result from the widespread detuning of the melt pressure sensors. The ADJ.PT is only used by the sensor alignment SE.CAL. |
| **UnIt** ▲▼ | **Setting up the physical unit, UNIT:**<br>**Default: NO**<br><br>UnIt [P]  C ▲▼ F ▲▼ L ▲▼ A ▲▼ U ▲▼ t ▲▼   no ▲▼ [P]<br><br>One can choose between the above shown physical units. It will be displayed on the 5th digit of the display. |

| Menu level | Parameterisation level |
|---|---|
| `SPCE` ⟳ | **Number of additional setpoints, SPCT:**<br>Default: 00<br><br>`0` ▲▼ `0` ▲▼ [P]<br><br>30 additional setpoints can be defined to the initial- and final value, so linear sensor values are not linearised. Only activated setpoint parameters are displayed. |
| `di 5.01` ⟳ | **Display values for setpoints, DIS.01 ... DIS.30:**<br><br>`8` [P] `8` [P] `8` [P] `8` [P] `8` ▲▼ \| `nOCA` / `CAL` ▲▼ [P]<br><br>Under this parameter setpoints are defined according to their value. At the sensor calibration, like at final value/offset, one is asked at the end if a calibration shall be activated. |
| `I nP.01` ⟳ | **Analog values for setpoints, INP.01 ... INP.30:**<br><br>`8` [P] `8` [P] `8` [P] `8` [P] `8` ▲▼ [P]<br><br>The setpoints are always preset according to the selected input signal mA/V. The demaned analog values can be freely adjusted in ascending order. |
| `di .Und` ⟳ | **Device undercut, DI.UND:**<br>Default: -19999<br><br>`8` [P] `8` [P] `8` [P] `8` [P] `8` ▲▼ [P]<br><br>With this function the device undercut (_ _ _ _ _) can be defined on a definite value. |
| `di .OUE` ⟳ | **Display overflow, DI.OUE:**<br>Default: 99999<br><br>`8` [P] `8` [P] `8` [P] `8` [P] `8` ▲▼ [P]<br><br>With this function the display overflow (‾‾‾‾‾) can be defined on a definite value. |
| `5 IG. In` ⟳ | Input variable of process value, SIG.IN:<br>**Default: A.MEAS**<br><br>`A.MEAS` ▲▼ `M.buS` ▲▼ [P]<br><br>With this parameter, the device can be controlled via the analog input signals A.MEAS = 10 VAC, 50 VAC respectively 1.5 AAC or via the digital signals of the interface M.BUS = RS232/RS485 (Modbus protocol). With **[P]** the selection is confirmed and the device changes into menu level. |
| `rEE` ⟳ | **Back to menu group level, RET:**<br><br><br>With **[P]** the selection is confirmed and the device changes into menu group level „-INP-". |

### 5.4.2. General device parameters

| Menu group level | | |
|---|---|---|
| -FCE- ▲▼ P → | | Menu level |

| Menu level | Parameterisation level |
|---|---|
| dl.SEC ▼▲ | **Display time, DISEC:** <br> Default: 01.0 <br><br> dl.SEC P `00.1` ▲▼ `00.9` then `01.0` ▲▼ `10.0` ▲▼ P <br><br> The display time is set up with **[▲] [▼]**. Thereby you switch up to 1 second in steps of 0.1 and up to 10.0 seconds in steps of 1.0. With **[P]** the selection is confirmed and the device changes into menu level. |
| round ▼▲ | **Rounding of display values, ROUND:** <br> Default: 00001 <br><br> round P `00001` ▲▼ `00005` ▲▼ `00010` ▲▼ `00050` ▲▼ P <br><br> This function is for instable display values, where the display value is changed in steps of 1, 5, 10 or 50. This does not affect the resolution of the optional outputs. With **[P]** the selection is confirmed and the device changes into menu level. |
| ArlEH ▼▲ | **Arithmetics, ARITH:** <br> Default: NO <br><br> ArlEH P `no` ▲▼ `rE2l P` ▲▼ `rAdl C` ▲▼ `SqUAr` P <br>                 Reciprocal      Root extraction     Square <br><br> With this function the calculated value, not the measuring value, is shown in the display. With NO, no calulation is deposited. With **[P]** the selection is confirmed and the device changes into menu level. |
| AVG ▼▲ | **Sliding average determination, AVG:** <br> **Default: 10** <br><br> AVG P `001` ▲▼ `100` ▲▼ P <br><br> Under this menu item, the number of measurements that need to be averaged are preset. The averaging time results from the product of measuring time SEC and the averaged measurements AVG. With selection of AVG in menu level DISPL the result is shown in the display and evaluated when entered in the alarm AL1-AL4 or the analog output OUTPT. |
| 2ErO ▼▲ | **Zero point slowdown, ZERO:** <br> Default: 00 <br><br> 2ErO P `0` P `0` ▲▼ P <br><br> At the zero point slowdown, a value range around the zero point can be preset, so the display shows a zero. If e.g.10 is set, the display would show a zero in the value range from -10 to +10; below continue with -11 and beyond with +11. The maximum adjustable range of value is 99. |

| Menu level | Parameterisation level |
|---|---|
| conSt ↑ ▼▲ ↓ | **Solid contstant value, CONST:**<br>Default: 0<br><br>8 [P] 8 [P] 8 [P] 8 [P] 8 ▲▼ [P]<br><br>The constant value can be evaluated like the current measurand via the alarms or the analog output. The decimal place cannot be changed for this value and is taken over from the current measurand. So, with this value a setpoint generator can be realised via the analog output. Furthermore it can be used as calculated difference. At this the constant value needs to be subtracted from the current measurand and the difference is evaluated in the alerting or via the analog output. Thus regulation can be displayed quite easy with this parameterisation. |
| conMI ↑ ▼▲ ↓ | **Minimum constant value, CON.MI:**<br>Default: -19999<br><br>8 [P] 8 [P] 8 [P] 8 [P] 8 ▲▼ [P]<br><br>The minimum constant value is selected and adjusted from the smallest to the highest digit with **[▲] [▼]** and confirmed digit per digit with **[P]**. A minus sign can only be adjusted on the highest digit. After the last digit the display changes back into menu level. |
| conMA ↑ ▼▲ ↓ | **Maximum constant value, CON.MA:**<br>Default: 99999<br><br>8 [P] 8 [P] 8 [P] 8 [P] 8 ▲▼ [P]<br><br>The maximum constant value is selected and adjusted from the smallest to the highest digit with **[▲] [▼]** and confirmed digit per digit with **[P]**. A minus sign can only be adjusted on the highest digit. After the last digit the display changes back into menu level. |
| dISPL ↑ ▼▲ ↓ | **Display, DISPL:**<br>Default: ACTUA<br><br>ActuA ▲▼ MIn.UA ▲▼ MAX.UA ▲▼ totAL ▲▼<br>HoLd ▲▼ AUG ▲▼ conSt ▲▼ dIFF ▲▼ [P]<br><br>With this function the current measuring value, the min-value/max-value, the totaliser, the process-controlled hold value, the sliding average value, the constant value or the difference between constant value and current value can be allocated to the display. With **[P]** the selection is confirmed and the device changes into menu level. |
| LIGHt ↑ ▼▲ ↓ | **Brightness control, LIGHT:**<br>Default: 15<br><br>00 ▲▼ 15 ▲▼ [P]<br><br>The brightness of the display can be adjusted in 16 levels from 00 = very dark to 15 = very bright via this parameter or alternatively via the navigation keys from the outside. During the start of the device the level that is deposited under this parameter will always be used, even though the brightness has been changed via the navigation keys in the meantime. |

| Menu level | Parameterisation level |
|---|---|
| **FLASH** [P] ▼ ▲ | **Display flashing, FLASH:** <br> Default: NO <br><br> no ▲▼ │ AL-1 ▲▼ │ AL-2 ▲▼ │ AL.12 ▲▼ <br><br> AL-3 ▲▼ │ AL-4 ▲▼ │ AL.34 ▲▼ │ AL.AL ▲▼ [P] <br><br> A display flashing can be added as additional alarm function either to single or to a combination of off-limit condition. With NO, no flashing is allocated. |
| **tASt** [P] ▼ ▲ | **Assignment (deposit) of key functions, TAST:** <br> Default: NO <br><br> EHtr ▲▼ │ LI.12 ▲▼ │ LI.34 ▲▼ │ tArA ▲▼ <br><br> SEt.tA ▲▼ │ totAL ▲▼ │ tot.rE ▲▼ │ EHt.rE ▲▼ <br><br> ActuA ▲▼ │ LIGHt ▲▼ │ LI.1 ▲▼ │ LI.1-2 ▲▼ <br><br> LI.1-3 ▲▼ │ LI.1-4 ▲▼ │ no ▲▼ [P] <br><br> For the operation mode, special functions can be deposited on the navigation keys **[▲] [▼]**, in particular this function is made for devices in housing size 48x24mm which do not have a 4th key (**[O]**-key). If the min/max-memory was activated by *EHTR*, all measured min/max-values are saved during operation and can be recalled via the navigation keys. The values get lost by restart of the device. If the threshold value correction *LI.12* or *LI.34* was choosen, the values of the threshold can be changed during operation without disturbing the operating procedure. With *TARA* the device is set temporarily on a parametrised value. The device acknowledges the correct taring with *00000* in the display. *SET.TA* switches into the offset value and can be adjusted via the navigation keys. Via *TOTAL* the current value of the totaliser can be displayed, after this the device switches back on the parameterised display value. If *TOT.RE* was deposited, the totaliser can be set back by pressing of the navigation keys **[▲] [▼]**, the device acknowledges this with showing *00000* in the display. By allocation on *EHT.RE* the min/max-memory is deleted. At *ACTUA* the measuring value is shown, after this the device switches back on the parameter-ised display value. With *LIGHT* the brightness of the display is adjusted. This setting is not saved and gets lost at a restart fo the device. Via selection *LI.1*, *LI.1-2*, *LI.1-3*, *LI.1-4*, in case of 8 switching points *LI.1-5…LI.1-8*, threshold values can be addressed via the navigation keys; they can be changed digit per digit or taken over by pushing the **[P]**-key. The adjustment is taken over directly, an excisting limit value monitoring and the current measurement will not be influenced by this. If *NO* is selected, the navigation keys are without any function in the operation mode. |

| Menu level | Parameterisation level |
|---|---|
| *ŁRSŁ.Ч* P ▼ ▲ | **Special function [O]-key,** *TAST.4*: **Default:** *NO*<br><br>*ŁRrR* ▲▼ *SEŁ.ŁR* ▲▼ *ŁoŁRL* ▲▼ *ŁoŁ.rE* ▲▼<br>*EHŁ.rE* ▲▼ *RcŁuR* ▲▼ *HoLd* ▲▼ *RuG* ▲▼<br>*SE.CRL* ▲▼ *conSŁ* ▲▼ *RL-1* ... *RL-4* ▲▼<br>*no* ▲▼ P<br><br>For the operation mode, special functions can be deposited on the **[O]**-key. This function is activated by pressing the key. With *TARA* the device is set temporarily on zero and saved permanently as offset. The device acknowledges the correct taring by showing *00000* in display. *SET.TA* switches into the offset value and can be adjusted via the navigation keys. Via *TOTAL* the current value of the totaliser can be displayed, after this the device switches back on the parameterised display value. If *TOT.RE* is deposited, the totaliser can be set back by pressing the navigation keys **[▲] [▼]**, the device acknowledges this with *00000* in the display. *EHT.RE* deletes the min/max-memory. If *HOLD* has been selected, the moment can be hold constant by pressing the **[O]**-key and is updated by releasing the key. **Advice**: *HOLD* is activated only, if *HOLD* was selected under parameter *DISPL*. *ACTUA* shows the measurand, after this the device switches back on the parameterised display value. The same goes for *AVG*, here the sliding average value will be displayed. Via *SE.CAL* a sensor calibration is done by pressing the zero key, the operating diagram is shown in *chapter 8*. The constant value *CONST* can be called up via the key or adjusted digit per digit. At *AL-1...AL-4* an output can be set and therewith can e.g. a setpoint adjustment be done. If *NO* is selected, the **[O]**-key is without any function in the operation mode. |
| *dl G.l n* P ▼ ▲ | **Special function digital input,** *DIG.IN*: **Default:** *NO*<br><br>*ŁRrR* ▲▼ *SEŁ.ŁR* ▲▼ *ŁoŁRL* ▲▼ *ŁoŁ.rE* ▲▼<br>*EHŁ.rE* ▲▼ *RcŁuR* ▲▼ *HoLd* ▲▼ *RuG* ▲▼<br>*SE.CRL* ▲▼ *conSŁ* ▲▼ *RL-1* ... *RL-4* ▲▼<br>*no* ▲▼ P<br><br>For the operation mode, the above shown parameters can be laid on the optional digital input, too. Functions description see *TAST.4*. |
| *rEŁ* ▲ ▼ ▲ | **Back to menu group level,** *RET*:<br><br><br>With **[P]** the selection is confirmed and the device changes into menu group level „-FCT-". |

### 5.4.3. Safety parameters
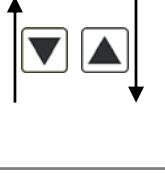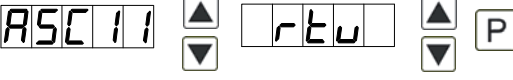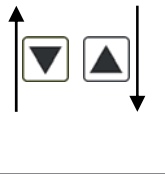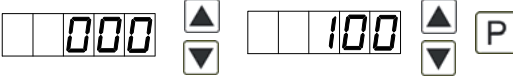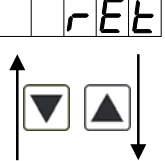
| Menu group level |
|---|
| -$Cod$- △▽ P → Menu level |

| Menu level | Parameterisation level |
|---|---|
| $U.CodE$ ▽△ | **Adjustment of user code, $U.CODE$ :** <br> **Default:** $0000$ <br><br> $U.CodE$ P $0$ P $0$ P $0$ P $0$ P $0$ △▽ P <br><br> Via this code reduced sets of parameters $OUT.LE$ and $AL.LEV$ can be unlocked during locked programming. Further parameters are not available via this code. The $U.CODE$ can only be changed via the correct input of the $A.CODE$ (Master code). |
| $A.CodE$ ▽△ | **Master code, $A.CODE$:** <br> **Default:** $1234$ <br><br> $A.CodE$ P $1$ P $2$ P $3$ P $4$ △▽ P <br><br> By entering $A.CODE$ the device will be released and all parameters unlocked. |
| $Out.LE$ ▽△ | **Release/lock analog output parameters, $OUT.LE$:** <br> **Default:** $ALL$ <br><br> $Out.LE$ P $no$ △▽ $En-OF$ △▽ $Out.EO$ △▽ $ALL$ △▽ P <br><br> Analog output parameters can be locked or released for the user: <br> - $EN-OF$: the initial or final value can be changed in operation mode <br> - $OUT.EO$: the output signal can be changed from e.g. 0-20 mA to 4-20 mA or 0-10 VDC <br> - $ALL$: analog output parameters are released <br> - $NO$: all analog output parameters are locked |
| $AL.LEV$ ▽△ | **Release/lock alarm parameters, $AL.LEV$:** <br> **Default:** $ALL$ <br><br> $AL.LEV$ P $no$ △▽ $LIMIT$ △▽ $ALrM.L$ △▽ $ALL$ △▽ P <br><br> This parameter describes the user release/user lock of the alarm: <br> - $LIMIT$: here only the range of value of the threshold values 1-4 can be changed <br> - $ALRM.L$: here the range of value and the alarm trigger can be changed <br> - $ALL$: all alarm parameters are released <br> - $NO$: all alarm parameters are locked |

| Menu level | Parameterisation level |
|---|---|
| ⬜⬜ r E t <br><br> ▼ ▲ | **Back to menu group level,** *RET:* <br><br><br><br> With **[P]** the selection is confirmed and the device changes into menu group level „*-COD-*". |

### 5.4.4. Serial parameters

**Menu group level**

-5Er- ▲▼ P ➝ Menu level

▼ ▲

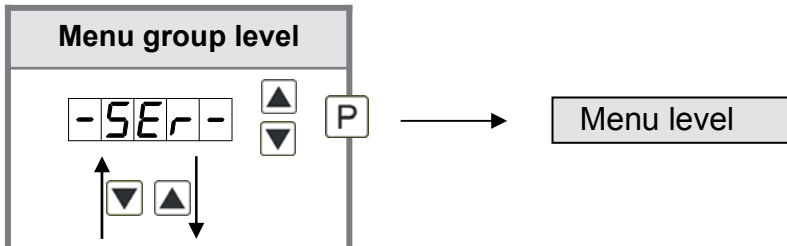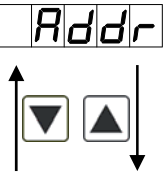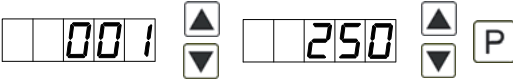| Menu level | Parameterisation level |
|---|---|
| ⬜ Addr ⬜ <br><br> ▼ ▲ | **Device address,** *ADDR:* <br> Default: *001* <br><br> Addr P ⬜⬜ 001 ▲▼ ⬜⬜ 250 ▲▼ P <br><br> The device address is adjusted from the smallest to the largest digit with the navigation keys **[▲] [▼]** and confirmed digit per digit with **[P]**. A device address up to max. 250 is available. Interface data: Baudrate 9600 bit/s, 8 databyte, 1 stopbit, no parity (8n1). |
| b.NOdE <br><br> ▼ ▲ | **ModBus operating modes,** *B.MODE:* <br> Default: *ASCII* <br><br> b.NOdE P ASCII ▲▼ ⬜ rtu ⬜ ▲▼ P <br><br> There are two different types of operating modes: *ASCII* and *RTU*. Modbus transfers no binary cycle, but the **ASCII**-Code. Thus it is directly readable, however the data throughput is smaller in comparison to the **RTU**. Modbus **RTU** (**RTU** = **R**emote **T**erminal **U**nit) transfers the data in binary-coded. This leads to a good data troughput, even though the data cannot be evaluated directly, as they first need to be transfered into a readable format. |
| tI.out P <br><br> ▼ ▲ | **Timeout,** *TIOUT:* <br> Default: *000* <br><br> tI.out P ⬜⬜ 000 ▲▼ ⬜⬜ 100 ▲▼ P <br><br> The monitoring of the data transfer is parameterised in seconds up to max. 100 seconds; there is no monitoring with an input of *000*. The timeout is adjusted from the smallest to the largest digit with the navigation keys **[▲] [▼]** and confirmed digit per digit with **[P]**. After the last digit the device changes back into menu level. |
| ⬜⬜ r E t <br><br> ▼ ▲ | **Back to menu group level,** *RET:* <br><br><br><br> With **[P]** the selection is confirmed and the device changes into menu group level „*-SER-*". |

## 5.4.5. Analog output parameters for analog output 1

**Menu group level**

`-Out-` ▲▼ P ⟶ Menu level
▼▲
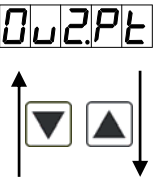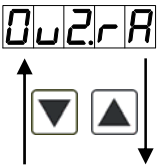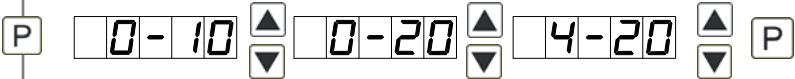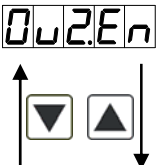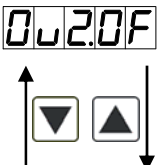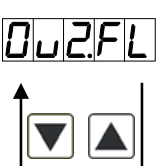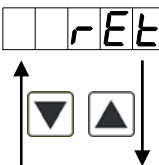
| Menu level | Parameterisation level |
|---|---|
| `OutPt` P ▼▲ | **Selection reference of analog output, OUTPT:**<br>Default: ACTUA<br><br>`ActuA` ▲▼ `MinUA` ▲▼ `MAXUA` ▲▼ `totAL` ▲▼<br>`HoLd` ▲▼ `AUG` ▲▼ `conSt` ▲▼ `diFF` ▲▼ P<br><br>The analog output signal can refer to different functions, in detail these are the current measurand, the min-value, the max-value, the totaliser function/sum function, the constant value or the difference between current measurand and constant value. If **HOLD** was selected, the signal of the analog output will be kept. It can be continued processing after a deactivation of **HOLD**. With **[P]** the selection is confirmed and the device changes into menu level. |
| `Out.rA` P ▼▲ | **Selection analog output, OUT.RA:**<br>Default: 4-20<br><br>`0-10` ▲▼ `0-20` ▲▼ `4-20` ▲▼ P<br><br>Three output signals are available 0-10 VDC, 0-20 mA and 4-20 mA. Select the desired signal with this function. |
| `Out.En` P ▼▲ | **Setting the final value of the analog output, OUT.EN:**<br>Default: 10000<br><br>`8` P `8` P `8` P `8` P `8` ▲▼ P<br><br>The final value is adjusted from the smallest to the highest digit with **[▲] [▼]** and confirmed digit per digit with **[P]**. A minus sign can only be parameterised on the highest digit. After the last digit the device changes back into menu level. |
| `Out.OF` P ▼▲ | **Setting the initial value of the analog output, OUT.OF:**<br>Default: 00000<br><br>`8` P `8` P `8` P `8` P `8` ▲▼ P<br><br>The initial value is adjusted from the smallest to the highest digit with **[▲] [▼]** and confirmed digit per digit with **[P]**. A minus sign can only be parameterised on the highest digit. After the last digit the device changes back into menu level. |

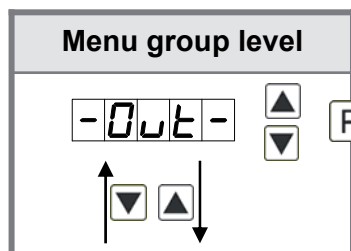| Menu level | Parameterisation level |
|---|---|
| `O.FLOU` [P] <br><br> ▼ ▲ | **Overflow behaviour, `O.FLOU`:** <br> Default: `EDGE` <br><br> `EdGE` ▲▼ `to.End` ▲▼ `to.OFF` ▲▼ `to.MI n` ▲▼ <br><br> `to.MAH` ▲▼ [P] <br><br> To recognise and evaluate faulty signals, e.g. by a controller, the overflow behaviour of the analog output can be defined. As overflow can be seen either `EDGE`, that means the analog output runs on the set limits e.g. 4 and 20 mA, or `TO.OFF` (input value smaller than initial value, analog output switches on e.g. 4 mA), `TO.END` (higher than final value, analog output switches on e.g. 20 mA). If `TO.MIN` or `TO.MAX` is set, the analog output switches on the smallest or highest possible binary value. This means that values of e.g. 0 mA, 0 VDC or values higher than 20 mA or 10 VDC can be reached. With **[P]** the selection is confirmed and the device changes into menu level. |
| `rEt` <br><br> ▼ ▲ | **Back to menu group level, `RET`:** <br><br><br> With **[P]** the selection is confirmed and the device changes into menu group level „-OUT-". |

**Analog output parameters for analog output 2**
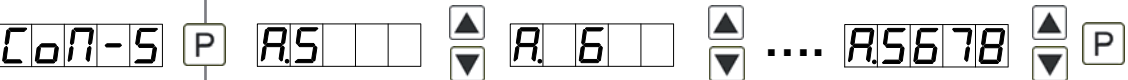
| Menu group level |
|---|
| `-Ou2-` ▲▼ [P] ⟶ [ Menu level ] <br><br> ▼ ▲ |

| Menu level | Parameterisation level |
|---|---|
| `Ou2.Pt` [P] <br><br> ▼ ▲ | **Selection reference of analog output, `OU2PT`:** <br> Default: `ACTUA` <br><br> `ActuA` ▲▼ `MI n.UA` ▲▼ `MAHUA` ▲▼ `totAL` ▲▼ <br><br> `HoLd` ▲▼ `AUG` ▲▼ `conSt` ▲▼ `d IFF` ▲▼ [P] <br><br> The analog output signal can refer to different functions, in detail these are the current measurand, the min-value, the max-value the totaliser function/sum function, the constant value or the difference between current measurand and constant value. If `HOLD` was selected, the signal of the analog output will be kept. It can be continued processing after a deactivation of `HOLD`. With **[P]** the selection is confirmed and the device changes into menu level. |

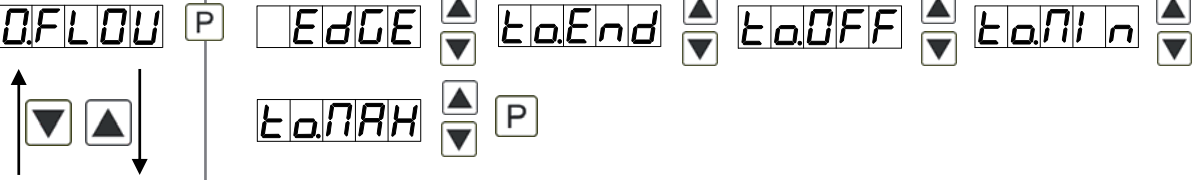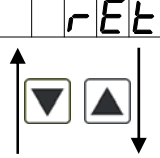| Menu level | Parameterisation level |
|---|---|
| $Ou2.rA$ ▼ ▲ | **Selection analog output, $OU2.RA$:**<br>Default: $4$-$20$<br><br>$0$-$10$ ▲▼  $0$-$20$ ▲▼  $4$-$20$ ▲▼  P<br><br>3 output signals are available 0-10 VDC, 0-20 mA and 4-20 mA. Select the desired signal with this function. |
| $Ou2.En$ ▼ ▲ | **Setting the final value of the analog output, $OU2.EN$:**<br>Default: $10000$<br><br>$8$ P $8$ P $8$ P $8$ P $8$ ▲▼ P<br><br>The final value is adjusted from the smallest to the highest digit with **[▲] [▼]** and confirmed digit per digit with **[P]**. A minus sign can only be parameterised on the highest digit. After the last digit the device changes back into menu level. |
| $Ou2.OF$ ▼ ▲ | **Setting the initial value of the analog output, $OU2.OF$:**<br>Default: $00000$<br><br>$8$ P $8$ P $8$ P $8$ P $8$ ▲▼ P<br><br>The initial value is adjusted from the smallest to the highest digit with **[▲] [▼]** and confirmed digit per digit with **[P]**. A minus sign can only be parameterised on the highest digit. After the last digit the device changes back into menu level. |
| $Ou2.FL$ ▼ ▲ | **Overflow behaviour, $OU2.FL$:**<br>Default: $EDGE$<br><br>$EdGE$ ▲▼  $to.End$ ▲▼  $to.OFF$ ▲▼  $to.MIn$ ▲▼<br>$to.MAX$ ▲▼ P<br><br>To recognise and evaluate faulty signals, e.g. by a controller, the overflow behaviour of the analog output can be defined. As overflow can be seen either $EDGE$, that means the analog output runs on the set limits e.g. 4 and 20 mA, or $TO.OFF$ (input value smaller than initial value, analog output switches on e.g. 4 mA), $TO.END$ (higher than final value, analog output switches on e.g. 20 mA). If $TO.MIN$ or $TO.MAX$ is set, the analog output switches on the smallest or highest possible binary value. This means that values of e.g. 0 mA, 0 VDC or values higher than 20 mA or 10 VDC can be reached. With **[P]** the selection is confirmed and the device changes into menu level. |
| $rEt$ ▼ ▲ | **Back to menu group level, $RET$:**<br><br>With **[P]** the selection is confirmed and the device changes into menu group level „$-OU2-$". |

### 5.4.6. Relay functions
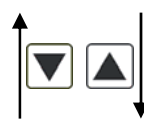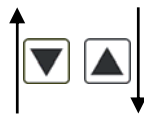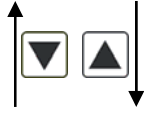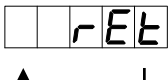
| Menu group level |
|---|

$-rEL-$   ▲▼  P  →  Menu level

| Menu level | Parameterisation level |
|---|---|
| $rEL-1$  P | **Alarm relay 1,** $REL\text{-}1$:           **The same applies for relays 2-4**<br>Default: $AL\text{-}1$<br><br>$AL\text{-}1$ .... $AL\text{-}4$ ▲▼ $AL\text{-}n1$ .... $AL\text{-}n4$ ▲▼<br><br>$LoGIC$ ▲▼ $OFF$ ▲▼ $On$ ▲▼ $CAL$ ▲▼<br><br>$CAL.OF$ ▲▼ $CAL.En$ ▲▼ P<br><br>Each setpoint (optional) can be linked up via 4 alarms (by default). This can either be inserted at activated alarms $AL1/4$ or deactivated alarms $ALN1/4$. If $LOGIC$ was selected, logical links are available in the menu level $LOG\text{-}1$ and $COM\text{-}1$. Access to these two menu levels is via $LOGIC$, at all other selected functions, these two parameters are overleaped. Via $ON/OFF$ the setpoints can be activated/deactivated, in this case the output and the setpoint display are set/not set on the front of the device. The parameters $CAL$, $CAL.OF$ and $CAL.EN$ can only be used in accordance with the semi-automatic calibration (*Chapter 9. Sensor alignment*). At $CAL$ the relay switches during sensor calibration, at $CAL.OF$ during offset calibration and at $CAL.EN$ during the calibration of the final value. With **[P]** the selection is confirmed and the device changes into menu level. |
| $LoG\text{-}1$  P | **Logic relay 1,** $LOG\text{-}1$<br>Default: $OR$<br><br>$or$ ▲▼ $nor$ ▲▼ $And$ ▲▼ $nAnd$ ▲▼ P<br><br>Here, the switching behaviour of the relay is defined via a logic link, the following schema describes these functions with inclusion of $AL\text{-}1$ and $AL\text{-}2$. This parameter can only be selected if $LOGIC$ was selected under $REL\text{-}1$. |

| | | |
|---|---|---|
| $or$ | $A1 \lor A2$ | As soon as a selected alarm is activated, the relay operates. Equates to operating current principle. |
| $nor$ | $\overline{A1 \lor A2} = \overline{A1} \land \overline{A2}$ | The relay operates only, if no selected alarm is active. Equates to quiescent current principle. |
| $And$ | $A1 \land a2$ | The relay operates only, if all selected alarms are active. |
| $nAnd$ | $\overline{A1 \land A2} = \overline{A1} \lor \overline{A2}$ | As soon as a selected alarm is not activated, the relay operates. |

With **[P]** the selection is confirmed and the device changes into menu level.

| Menu level | Parameterisation level |
|---|---|
| `CoN-1` [P] ▼ ▲ | **Alarms for relay 1, `CON-1`:**<br>Default: `A.1`<br><br>`CoN-1` [P]  `A.1` ▲▼  `A. 2` ▲▼  …. `A.1234` ▲▼ [P]<br><br>The allocation of the alarms to relay 1 happens via this parameter, one alarm or a group of alarms can be chosen. With **[P]** the selection is confirmed and the device changes into menu level. |
| `rEL-5` [P] ▼ ▲ | **Alarm relay 5, `REL-5`:**　　　　　　　　　　　　　　　**The same applies for relays 6-8**<br>Default: `AL-5`<br><br>`rEL-5` [P]　`AL-5` …. `AL-8` ▲▼  `AL-n5` …. `AL-n8` ▲▼<br><br>`LoGIC` ▲▼　`OFF` ▲▼　`On` ▲▼　`CAL` ▲▼<br><br>`CAL.OF` ▲▼　`CAL.En` ▲▼ [P]<br><br>Each setpoint (optional) can be linked up via 4 alarms (by default). This can either be inserted at activated alarms `AL6/8` or deactivated alarms `ALN6/8`. If `LOGIC` is selected, logical links are available in the menu level `LOG-1` and `COM-1`. Access to these two menu levels is via `LOGIC`, at all other selected functions, these two parameters are overleaped. Via `ON/OFF` the setpoints can be activated/deactivated, in this case the output and the setpoint display are set/not set on the front of the device. The parameters `CAL`, `CAL.OF` and `CAL.EN` can only be used in accordance with the semi-automatic calibration (*Chapter 9. Sensor alignment*). At `CAL` the relay switches during sensor calibration, at `CAL.OF` during offset calibration and at `CAL.EN` during the calibration of the final value. With **[P]** the selection is confirmed and the device changes into menu level. |
| `LoG-5` [P] ▼ ▲ | **Logic relay 5, `LOG-5`:**<br>Default: `OR`<br><br>`LoG-5` [P]　`or` ▲▼　`nor` ▲▼　`And` ▲▼　`nAnd` ▲▼ [P]<br><br>Here, the switching behaviour of the relay is defined via a logic link, the following schema describes these functions with inclusion of `AL-1` and `AL-2`: |

| | | |
|---|---|---|
| `or` | $A1 \lor A2$ | As soon as a selected alarm is activated, the relay operates. Equates to operating current principle. |
| `nor` | $\overline{A1 \lor A2} = \overline{A1} \land \overline{A2}$ | The relay operates only, if no selected alarm is active. Equates to quiescent current principle. |
| `And` | $A1 \land a2$ | The relay operates only, if all selected alarms are active. |
| `nAnd` | $\overline{A1 \land A2} = \overline{A1} \lor \overline{A2}$ | As soon as a selected alarm is not activated, the relay operates. |

With **[P]** the selection is confirmed and the device changes into menu level.

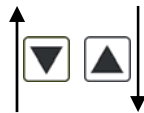| Menu level | Parameterisation level |
|---|---|
| `CoN-5` [P]  ⬆⬇ | **Alarms for relay 5, `COM-5`:** <br> Default: `A.5` <br><br> `A.5` ⬆⬇ `A. 6` ⬆⬇ .... `A.5678` ⬆⬇ [P] <br><br> The allocation of the alarms to relay 5 happens via this parameter, one alarm or a group of alarms can be chosen. With **[P]** the selection is confirmed and the device changes into menu level. |
| `rEt` ⬆⬇ | **Back to menu group level, `RET`:** <br><br><br><br> With **[P]** the selection is confirmed and the device changes into menu group level „-REL-". |

## 5.4.7. Alarm parameters

**Menu group level**

`-AL 1-` ⬆⬇ [P] ⟶ Menu level

| Menu level | Parameterisation level |
|---|---|
| `ALrN.1` [P]  ⬆⬇ | **Dependency alarm 1, `ALRM.1`:** <br> Default: `ACTUA` <br><br> `ActuA` ⬆⬇ `MInUA` ⬆⬇ `MAHUA` ⬆⬇ `totAL` ⬆⬇ <br><br> `HoLd` ⬆⬇ `AUG` ⬆⬇ `conSt` ⬆⬇ `d IFF` ⬆⬇ <br><br> `EHtEr` ⬆⬇ [P] <br><br> The dependency of `ALARM.1` can be related to special functions, in detail these are the current measurand, the min-value, the max-value, the totaliser value/sum value, the constant value or the difference between the current measurand and the constant value. If `HOLD` was selected, the alarm is hold and processed just after deactivation of `HOLD`. `EHTER` causes the dependency either by pressing the **[O]**-key on the front of the housing or by an external signal via the digital input. With **[P]** the selection is confirmed and the device changes into menu level. <br> **Example:** <br> By using the maximum value `ALARM.1` = `MAX.VA` in combination with a threshold monitoring `FU-1` = `HIGH`, an alarm confirmation can be realised. Use the navigation keys, the 4th key or the digital input for confirmation. |

| Menu level | Parameterisation level |
|---|---|
| **L I-1** ▼ ▲ | **Threshold values / limit values, _LI-1_:** <br> Default: _2000_ <br><br> **L I-1** P **0** P **0** P **0** P **0** P **0** ▲▼ P <br><br> The limit value defines the threshold, that activates/deactivates an alarm. |
| **HY-1** ▼ ▲ | **Hysteresis for threshold values, _HY-1_:** <br> Default: _00000_ <br><br> **HY-1** P **0** P **0** P **0** P **0** P **0** ▲▼ P <br><br> The delayed reaction of the alarm is the difference to the threshold value, which is defined by the hysteresis. |
| **Fu-1** ▼ ▲ | **Function for threshold value undercut / exceedance, _FU-1_:** <br> Default: _HIGH_ <br><br> **Fu-1** P **HIGH** ▲▼ **Louu** ▲▼ P <br><br> A limit value undercut is selected with _LOUU_ (for LOW = lower limit value), a limit value exceedance with _HIGH_ (for HIGH = higher limit value). If e.g. limit value 1 is on a threshold level of 100 and allocated with function _HIGH_, an alarm is activated by reaching of the threshold level. If the threshold value was allocated to _LOW_, an alarm will be activated by undercutting the threshold value, as long as the hysteresis is zero. |
| **ton-1** ▼ ▲ | **Switching-on delay, _TON-1_:** <br> Default: _000_ <br><br> **ton-1** P **0** P **0** P **0** ▲▼ P <br><br> For limit value 1 one can preset a delayed switching-on of 0-100 seconds. |
| **toF-1** ▼ ▲ | **Switching-off delay, _TOF-1_:** <br> Default: _000_ <br><br> **toF-1** P **0** P **0** P **0** ▲▼ P <br><br> For limit value 1 one can preset a delayed switching-off of 0-100 seconds. |
| **rEt** ▼ ▲ | **Back to menu group level, _RET_:** <br><br> With **[P]** the selection is confirmed and the device changes into menu group level „_-AL1-_". |
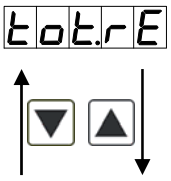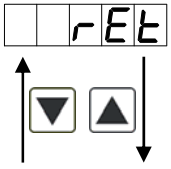
**The same applies for _AL2_ to _AL8_.**

### 5.4.8. Totaliser (Volume metering)

**Menu group level**



| Menu level | Parameterisation level |
|---|---|
|  | **State of totaliser,** _TOTAL:_ <br> **Default:** _OFF_ <br><br>  <br><br> The totaliser realizes measurements on a time base of e.g. l/h, at this the scaled input signal is integrated by a time and steadily (select _STEAD_) or temporarily (select _TEMP_) safed. Select the constant storage for consumption measurements and the quick storage for frequently filling processes. During the constant storage _STEAD_ the current sum value is saved at each totaliser reset. Furthermore it is saved every 30 minutes in the not-quick storage of the device. If _OFF_ is selected, the function is deactivated. With **[P]** the selection is confirmed and the device changes into menu level. |
|  | **Time base,** _T.BASE:_ <br> Default: _SEC_ <br><br>  <br><br> Under this parameter the time base of the measurement can be preset in seconds, minutes or hours. |
|  | **Totaliser factor,** _FACTO:_ <br> Default: _1E0_ <br><br>  <br><br> At this the factor (1E0…1E6) respectively the divisor for the internal calculation of the measuring value is assigned. |
|  | **Setting up the decimal point for the totaliser,** _TOT.DT:_ <br> Default: _0_ <br><br>  <br><br> The decimal point of the device can be adjusted with the navigation keys **[▲] [▼]**. With **[P]** the selection is confirmed and the device changes into menu level. |

| Menu level | Parameterisation level |
|---|---|
| `tot.rE` ▼ ▲ | **Totaliser reset,** *TOT.RE*: Default: *00000*<br><br>`8` P `8` P `8` P `8` P `8` ▲▼ P<br><br>The reset value is adjusted from the smallest to the highest digit with the navigation keys **[▲] [▼]** and digit per digit confirmed with **[P]**. After the last digit, the display switches back to the menu level. The activator for the reset is parameter driven via the 4th key or via the optional digital input. |
| `rEt` ▼ ▲ | **Back to menu group level,** *RET*:<br><br><br>With **[P]** the selection is confirmed and the device changes into menu group level „–TOT–". |

## Programming interlock, *RUN*:

| Menu group level |
|---|
| `-run-` ▲▼ P ▼ ▲ |
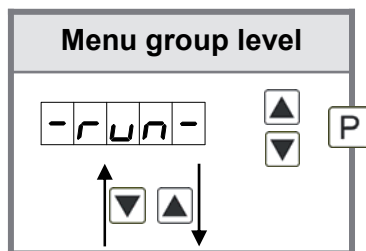
Description see page 9, menu level *RUN*

# 6. Reset to default values

To return the unit to a **defined basic state**, a reset can be carried out to the default values.

The following procedure should be used:

• Switch off the power supply
• Press button **[P]**
• Switch on voltage supply and press **[P]**-button until „- - - - -" is shown in the display.

With reset, the default values of the program table are loaded and used for subsequent operation. This sets the unit back to the state in which it was supplied.

**Caution! All application-related data are lost.**

# 7. Alarms / Relays

This device has 8 virtual alarms that can monitor one limit value in regard of an undercut or exceedance. Each alarm can be allocated to an optional relay output S1-S4; furthermore alarms can be controlled by events like e.g. Hold or min/max-value.

| Function principle of alarms / relays | |
|---|---|
| **Alarm / Relay x** | Deactivated, instantaneous value, min/max-value, hold-value, totaliser value, sliding average value, constant value, difference between instantaneous value and constant value or an activation via the digital input or the **[O]**-key |
| **Switching threshold** | Threshold / limit value of the change-over |
| **Hysteresis** | Broadness of the window between the switching thresholds |
| **Working principle** | Operating current / quiescent current |
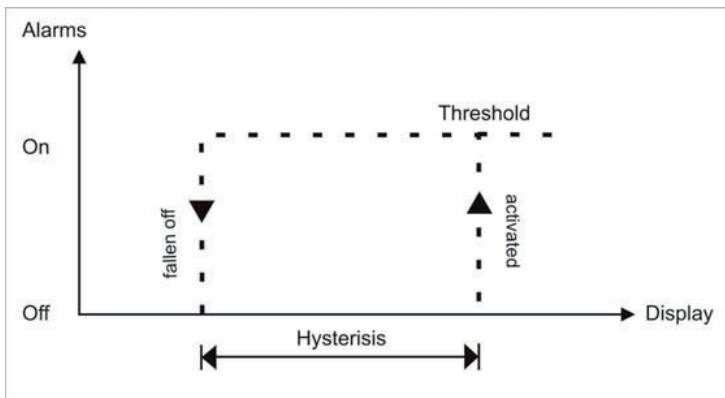


**Operating current**
By operating current the alarm S1-S4 is **off** below the threshold and **on** on reaching the threshold.
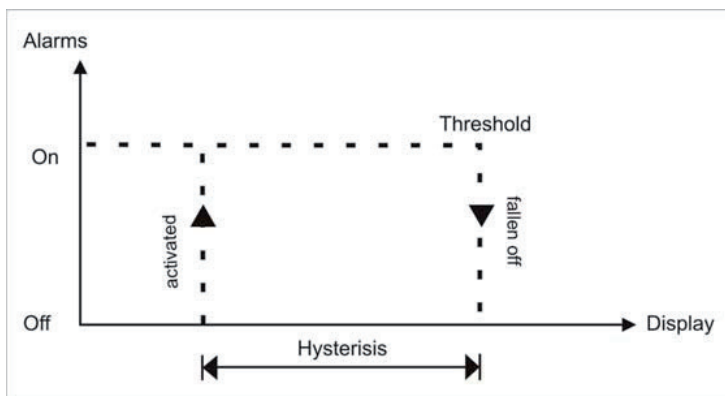


**Quiescent current**
By quiescent current the alarm S1-S4 is **on** below the threshold and switched **off** on reaching the threshold.
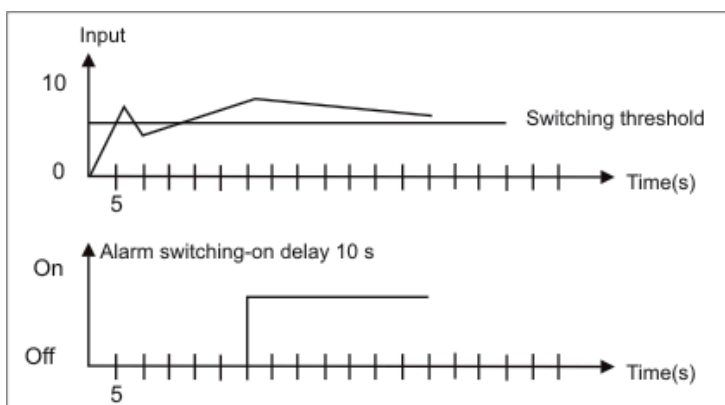


**Switching-on delay**
The switching-on delay is activated via an alarm and e.g. switched 10 seconds after reaching the switching threshold, a short-term exceedance of the switching value does not cause an alarm, respectively does not cause a switching operation of the relay. The switching-off delay operates in the same way, keeps the alarm / the relay switched longer for the parameterised time.

# 8. Interfaces

## Connection RS232

Digital device M3                    PC - 9-pole Sub-D-plug

| 14 | RxD | TxD | 2 |
| 15 | TxD | RxD | 3 |
| 16 | GND | GND | 5 |

## Connection RS485

Digital device M3

120 Ω          PC

| 14 | DATA A (-) |
| 15 | DATA B (+) |
| 16 | GND |
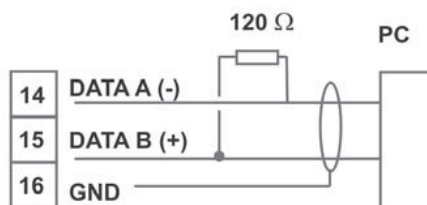
The interface **RS485** is connected via a screened data line with twisted wires (Twisted-Pair). On each end of the bus segment a termination of the bus lines needs to be connected. This is neccessary to ensure a secure data transfer to the bus. For this a resistance (120 Ohm) is interposed between the lines Data B (+) and Data A (–).

# 9. Sensor alignment offset / final value

The device is equipped with a semi-automatic sensor calibration (*SRXXX*). A switching output operates the trimming resistor, which exists in some sensors. An adjustment of offset and final value takes place, after which the sensor can be used directly. Depending on parameterisation, the calibration can be realized via the 4th key or via the digital input. It is possible to key during the calibration steps. So, reference signals can be connected manually. However the calibration will be interrupted after 30 seconds.

Press actuator for minimum 3 seconds.

**CAL.OF** — Activate optional switching output.

For minimum 1 measuring cycle, minimum 1s or maximum per actuator.

**0.061** — Current measuring range value, e.g. *0.061*

For calibration problems or 30 seconds holding time.

For minimum 1 measuring cycle or with actuator.

**CAL.En** — Switch-off/switch-on optional switching output, e.g. 7,132

For minimum 1 measuring cycle, minimum 1s or maximum per actuator.

**7.132** — Current measuring range value.

For calibration problems or 30 seconds holding time.

For minimum 1 measuring cycle, minimum 1s or maximum per actuator.

**C.FAIL**

**C.SAVE** — Optional: switch-off switching output and display for minimum 1 measuring cycle or minimum 1s holding time.

Back to regular operation mode.

Back to regular operation mode, after 1s or 1 measuring cycle.

# 10. Technical data

| Housing | |
|---|---|
| **Dimensions** | 96x48x120 mm (BxHxD) |
| | 96x48x139 mm (BxHxD) incl. plug-in terminal |
| Panel cut-out | $92.0^{+0.8}$ x $45.0^{+0.6}$ mm |
| Wall thickness | up to 15 mm |
| Fixing | screw elements |
| Material | PC Polycarbonate, black, UL94V-0 |
| Sealing material | EPDM, 65 Shore, black |
| Protection class | standard IP65 (Front), IP00 (Back side) |
| Weight | approx. 300 g |
| Connection | plug-in terminal; wire cross-section up to 2.5 mm$^2$ |
| **Display** | |
| Digit height | 14 mm |
| Segment colour | red (optional green, orange or blue) |
| Display range | -19999 up to 99999 |
| Setpoints | one LED per setpoint |
| Overflow | horizontal bars at the top |
| Underflow | horizontal bars at the top |
| Display time | 0.1 to 10.0 seconds |

| Input | Measuring range | Measuring error | Digit |
|---|---|---|---|
| 0…1,1 kΩ | 0…1 kΩ | 0.5 % of measuring range | ±1 |
| 0…11 kΩ | 0…10 kΩ | 0.5 % of measuring range | ±1 |
| 0…110 kΩ | 0…100 kΩ | 0.5 % of measuring range | ±1 |
| Digital input | < 2.4 V OFF, 10 V ON, max. 30 VDC  $R_I \sim 5$ kΩ | | |
| | | | |

| Accuracy | |
|---|---|
| Temperature drift | 100 ppm / K |
| Measuring time | 0.1…10.0 seconds |
| Measuring principle | U/F-conversion |
| Resolution | approx. 18 bit at 1s measuring time |

| Output | |
|---|---|
| Analog output | 0/4-20 mA / burden ≤500 Ω; 0-10 VDC / burden ≥10 kΩ, 16 bit |

| Switching outputs | |
|---|---|
| Relay with change-over contacts Switching cycles | 250 VAC / 5 AAC; 30 VDC / 5 ADC<br>$30 \times 10^3$ at 5 AAC, 5 ADC ohm resistive burden<br>$10 \times 10^6$ mechanically<br>Diversification according to DIN EN50178 /<br>Characteristics according to DIN EN60255 |
| PhotoMos-outputs | Closer contacts: 30 VDC/AC, 0.4 A |

| Interface | |
|---|---|
| Protocol | Modbus with ASCII or RTU-protocol |
| RS232 | 9.600 Baud, no parity, 8 Databit, 1 Stopbit,<br>cable length max. 3 m |
| RS485 | 9.600 Baud, no parity, 8 Databit, 1 Stopbit,<br>cable length max. 1000 m |

| Power supply | |
|---|---|
| | 100-240 VAC 50/60 Hz, DC ± 10% (max. 15 VA)<br>10-40 VDC galv. isolated, 18-30 VAC 50/60 Hz (max. 15 VA) |

| Memory | EEPROM |
|---|---|
| Data life | ≥ 100 years / 25°C |

| Ambient conditions | |
|---|---|
| Working temperature | 0…50°C |
| Storing temperature | -20…80°C |
| Wheatering resistance | relative humidity 0-80% on years average without dew |

| EMV | EN 61326, EN 55011 |
|---|---|

| CE-sign | Conformity according to directive 2004/108/EG |
|---|---|

| Safety standard | According to low voltage directive 2006/95/EG<br>EN 61010; EN 60664-1 |
|---|---|

# 11. Safety advices

Please read the following safety advices and the assembly *chapter 2* before installation and keep it for future reference.

**Proper use**

The **DAL-311-**-device is designed for the evaluation and display of sensor signals.

⚠ **Attention! Careless use or improper operation can result in personal injury and/or cause damage to the equipment.**

**Control of the device**

The panel meters are checked before dispatch and sent out in perfect condition. Should there be any visible damage, we recommend close examination of the packaging. Please inform the supplier immediately of any damage.

**Installation**

The **DAL-311-device** must be installed by a suitably qualified specialist (e.g. with a qualification in industrial electronics).

**Notes on installation**

• There must be no magnetic or electric fields in the vicinity of the device, e.g. due to transformers, mobile phones or electrostatic discharge.

• The **fuse rating** of the supply voltage should not exceed a value of **6A N.B. fuse**.

• Do not install **inductive consumers** (relays, solenoid valves etc.) near the device and **suppress** any interference with the aid of RC spark extinguishing combinations or free-wheeling diodes.

• Keep input, output and supply lines separate from one another and do not lay them parallel with each other. Position "go" and "return lines" next to one another. Where possible use twisted pair. So, you receive best measuring results.

• Screen off and twist sensor lines. Do not lay current-carrying lines in the vicinity. Connect the **screening on one side** on a suitable potential equaliser (normally signal ground).

• The device is not suitable for installation in areas where there is a risk of explosion.

• Any electrical connection deviating from the connection diagram can endanger human life and/or can destroy the equipment.

• The terminal area of the devices is part of the service. Here electrostatic discharge needs to be avoided. Attention! High voltages can cause dangerous body currents.

• Galvanic isolated potentials within one complex need to be placed on an appropriate point (normally earth or machines ground). So, a lower disturbance sensibility against impacted energy can be reached and dangerous potentials, that can occur on long lines or due to faulty wiring, can be avoided.

# 12. Error elimination

| | Error description | Measures |
|---|---|---|
| 1. | The unit permanently indicates overflow.<br><br>⎺ ⎺ ⎺ ⎺ ⎺ | • The input has a very high measurement, check the measuring circuit.<br>• With a selected input with a low voltage signal, it is only connected on one side or the input is open.<br>• Not all of the activated setpoints are parameterised. Check if the relevant parameters are adjusted correctly. |
| 2. | The unit permanently shows underflow.<br><br>⎽ ⎽ ⎽ ⎽ ⎽ | • The input has a very low measurement, check the measuring circuit.<br>• With a selected input with a low voltage signal, it is only connected on one side or the input is open.<br>• Not all of the activated setpoints are parameterised. Check if the relevant parameters are adjusted correctly. |
| 3. | The word *HELP* lights up in the 7-segment display. | • The unit has found an error in the configuration memory. Perform a reset on the default values and reconfigure the unit according to your application. |
| 4. | Program numbers for parameterising of the input are not accessible. | • Programming lock is activated.<br>• Enter correct code. |
| 5. | *ERR1* lights up in the 7-segment display. | • Please contact the manufacturer if errors of this kind occur. |
| 6. | The device does not react as expected. | • If you are not sure that the device has been parameterised before, then follow the steps as written in *chapter 6* and set it back to its delivery status. |

| | | | | | | | |
|---|---|---|---|---|---|---|---|
| fill level | water level | pressure | temperature | flow | visualization | signal converter | sensoric |

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